

PILOT Midterm 1 Review

Differential Equations

Johns Hopkins University

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As you prepare for the midterm, please consider the following resources:

- PILOT webpage for ODEs:
<https://jhu-ode-pilot.github.io/SP25/>
 - The first 5 problem sets will be associated with this midterm. (Except for the last question on PSet 5.)
 - Find the review problem set for midterm 1.
- Review the *homework sets* provided by the instructor.
- Join the PILOT Midterm 1 Review Session. (You are here.)

Plan for today:

- 1 Go over all contents that we have covered for this semester so far.
- 2 In the end, we will open the poll to you. Please indicate which problems from the PSets or Review Set that you want us to go over.

Contents:

1 Preliminaries

- Classifications of Differential Equations
- Modeling Using ODEs
- Half Life Problems

2 First Order ODEs

- Integrating Factor
- Separable ODEs
- Existence and Uniqueness
- Autonomous ODEs
- Logistic Population Growth
- Exactness Problem
- Bifurcation

3 Review Problems

Part 1:

Contents Review

We will get through all contents over this semester.

- Feel free to download the slide deck from the webpage and annotate on it.
- If you have any questions, ask by the end of each chapter.

Differential equations can be classified by their properties:

- Ordinary Differential Equations (ODEs) involves ordinary derivatives ($\frac{dy}{dt}$), while Partial Differential Equations (PDEs) involves partial derivatives ($\frac{\partial y}{\partial t}$).
- Single equation involves one unknown and one equation, while System of equations involves multiple unknowns and multiple equations.
- The order of the differential equation is the order of the highest derivatives term.
- Linear differential equations has only linear dependent on the function, while non-linear differential equations has non-linear dependent on the function.

ODEs can be used for modeling. During modeling, it follows the following steps:

- 1 Construction of the Models,
- 2 Analysis of the Models,
- 3 Comparison of the Models with Reality.

The physics model for half life indicates the relationship between half life (τ) of a substance of amount $N(t)$ with initial amount N_0 at a time t is:

$$N(t) = N_0 \left(\frac{1}{2} \right)^{\frac{t}{\tau}},$$

where the rate of decay (λ) and half life (τ) are related by:

$$\tau \times \lambda = \log 2.$$

For ODEs in form $\frac{dy}{dt} + a(t)y = b(t)$, the integrating factor is:

$$\mu(t) = \exp \left(\int a(t) dt \right).$$

For ODEs in form $M(t) + N(y) \frac{dy}{dt} = 0$, it can be separated by:

$$M(t)dt + N(y)dy = 0.$$

The existence and uniqueness for Initial Value Problem (IVP) depend on cases:

- For an IVP in simple form:

$$\begin{cases} \frac{dy}{dt} = a(t)y + b(t), \\ y(t_0) = y_0. \end{cases}$$

If $a(t)$ and $b(t)$ are continuous on an interval (α, β) and $t_0 \in (\alpha, \beta)$. Then, there exists a uniqueness solution y for (α, β) to the IVP.

Picard's Theorem

- For an IVP in general form:

$$\begin{cases} \frac{dy}{dt} = f(t, y), \\ y(t_0) = y_0. \end{cases}$$

For $t_0 \in I = (a, b)$, $y_0 \in J = (c, d)$, if $f(t, y)$ and $\frac{\partial f}{\partial y}(t, y)$ are continuous on interval $I \times J$. Then, there exists a unique solution on a smaller interval $I' \times J' \subset I \times J$, in which $(t_0, y_0) \in I' \times J'$.

Autonomous ODEs are in form of:

$$\frac{dy}{dt} = f(y).$$

The stability (stable/semi-stable/unstable) of equilibrium can be determined by phase lines, *i.e.*, the zeros of the function $f(t)$.

Rational Root Test

Let the polynomial with integer coefficients be defined as:

$$a_n x^n + a_{n-1} x^{n-1} + \cdots + a_0 = 0,$$

then any rational root $r = p/q$ such that $p, q \in \mathbb{Z}$ and $\gcd(p, q) = 1$ satisfies that $p|a_0$ and $q|a_n$.

The logistic population growth model with population (y), growing rate (r), and carrying capacity (k) is given by:

$$\begin{cases} \frac{dy}{dt} = r \left(1 - \frac{y}{k}\right) y, \\ y(0) = y_0. \end{cases}$$

The solution for Logistic Population Growth is:

$$y(t) = \frac{ky_0}{(k - y_0)e^{-rt} + y_0}.$$

The condition for a function in form $M(x, y) + N(x, y) \frac{dy}{dx} = 0$ to be exact is:

$$\frac{\partial N}{\partial x} = \frac{\partial M}{\partial y}.$$

For solving Exact ODEs, either finding $\int M(x, y)dx + h(y)$ or $\int N(x, y)dy + h(x)$ and taking partials again to fit gives the solution $\Psi(x, y) = C$.

For not exact cases, the integrating factor is:

$$\mu(t) = \exp \left(\int \frac{M_y - N_x}{N} dx \right) \quad \text{or} \quad \mu(t) = \exp \left(\int \frac{N_x - M_y}{M} dy \right).$$

When a differential equation contains some parameter c , its equilibriums would exhibit different behavior, the bifurcation value is the critical value such that the equilibriums have different stability.

A bifurcation diagram is the vertical concatenation of phase portraits (C - y plot), in which the equilibriums will be marked for respective values of C .

Part 2: Open Poll

We will work out some sample questions.

- If you have a problem that you are interested with, tell us now.
- Otherwise, we will work through the practice problem set sequentially.
- We are also open to conceptual questions with the course.

- 1 Find the general solution for $y = y(t)$:

$$y' + 3y = t + e^{-2t},$$

then, describe the behavior of the solution as $t \rightarrow \infty$.

- 2 Given an initial value problem:

$$\begin{cases} \frac{dy}{dt} - \frac{3}{2}y = 3t + 2e^t, \\ y(0) = y_0. \end{cases}$$

- 1 Find the integrating factor $\mu(t)$.
- 2 Solve for the particular solution for the initial value problem.
- 3 Discuss the behavior of the solution as $t \rightarrow \infty$ for different cases of y_0 .

- 3 An autonomous differential equation is given as follows:

$$\frac{dy}{dt} = 4y^3 - 12y^2 + 9y - 2 \quad \text{where } t \geq 0 \text{ and } y \geq 0.$$

Draw a phase portrait and sketch a few solutions with different initial conditions.

- 4 Determine if the following differential equation is exact. If not, find the integrating factor to make it exact. Then, solve for its general solution:

$$y'(x) = e^{2x} + y(x) - 1.$$

- 5 For the first-order autonomous ODE:

$$\frac{dy}{dt} = \sin y + C,$$

where $C \in \mathbb{R}$ is a parameter. Determine any and all bifurcation values for the parameter C and sketch a bifurcation diagram.

- 6 Let an initial value problem be defined as follows:

$$\begin{cases} (12x^4 + 5x^2 + 6) \frac{dy}{dx} - (x^2 \sin(x) + x^3)y = 0, \\ y(0) = 1. \end{cases}$$

Show that the solution to the above initial value problem is symmetric about $x = 0$.

Good luck on your first midterm exam.